# The Universality of the diagonal model, or the Abelianization of the Gauss constraint in Loop Quantum Cosmology

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# Two points program

- Introduction to nondiagonal Bianchi models
  - Minisuperspace and Ashtekar variables
  - Flux quantization procedure

[Montani, MB '23] [gr-qc] 2302.03638

- Abelianization of the Gauss constraint
  - Gauge freedom and canonical transformation
  - Revised Gauss Constraint and Quantum-level implications

[Montani, MB '23] [gr-qc] 2306.10934

## Minisuperspace

Globally hyperbolic spacetime  $\mathcal{M} = \mathbb{R} \times \Sigma$ 

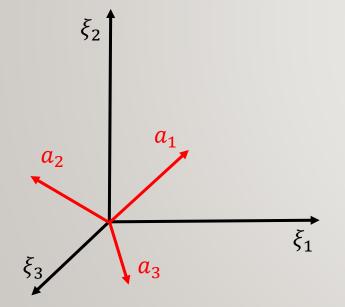
[Landau, Lifshits '74] [Belinski '14] [Montani, MB '23]

Homogeneous space  $\Sigma$  prescription  $q_{ij}(t,x) = \eta_{IJ}(t)\omega_i^I(x)\omega_i^J(x)$ 

$$q_{ij}(t,x) = \eta_{IJ}(t)\omega_i^I(x)\omega_j^J(x)$$

Nondiagonal metric decomposition

$$\eta_{IJ} = \Gamma_{\!AB} R_I^A R_J^B$$



Maurer-Cartan equation Lie algebra generators 
$$d\omega^I + \frac{1}{2} f^I_{JK} \omega^J \omega^K = 0 \qquad \left[ \xi_I, \xi_J \right] = f^K_{IJ} \xi_K$$

Lie algebra generators 
$$\left[\xi_I, \xi_J\right] = f_{IJ}^K \xi_K$$

Metric configuration variables

$$\{a_1, a_2, a_3, \theta, \psi, \phi\}$$

#### Ashtekar variables

#### Lagrangian

$$\begin{split} &L_{ADM} \\ &= N |\det(\omega_{i}^{I})| \sqrt{\det(\Gamma_{AB})} \left[ \bar{R} + \frac{1}{4N^{2}} (\Gamma^{AC}\Gamma^{BD}\dot{\Gamma}_{AB}\dot{\Gamma}_{CD} + 2\Gamma^{AB}\Gamma_{CD}(R\dot{\Lambda})_{A}^{D}(R\dot{\Lambda})_{B}^{C} + 2(R\dot{\Lambda})_{C}^{B}(R\dot{\Lambda})_{B}^{C} \right. \\ &+ 2N^{A}N^{B} \left( f_{AJ}^{I} f_{BI}^{J} + \eta^{IJ}\eta_{KL} f_{AI}^{K} f_{BJ}^{L} \right) + 4N^{K}\eta^{IJ}\dot{\eta}_{JL} f_{KI}^{L} - \Gamma^{IJ}\dot{\Gamma}_{IJ}\Gamma^{KL}\dot{\Gamma}_{KL} ) \right] \end{split}$$

#### Ashtekar connection

$$A_i^a = \left[\frac{1}{2}\epsilon^{abc}\frac{a_c}{a_b}\Lambda_b^JR_K^cf_{IJ}^K - \frac{1}{4}\epsilon^{abc}\frac{1}{a_ba_c}\eta_{IJ}\Lambda_b^K\Lambda_c^Lf_{LK}^J + \frac{\gamma}{2N}a_{(a)}R_L^a\left(\eta^{LJ}\dot{\eta}_{JI} + N^A\eta^{LK}\eta_{IJ}f_{AK}^J + N^Af_{AI}^L\right)\right]\omega_i^I$$

#### Electric field

$$E_a^i = |\det(\omega_i^I)| \operatorname{sgn}(a_{(a)}) |a_b a_c| \Lambda_a^I \xi_I^i$$

#### Ashtekar variables

#### Lagrangian

$$L_{ADM} = N |\det(\omega_{i}^{I})| \sqrt{\det(\Gamma_{AB})} \left[ \bar{P} + \frac{1}{4N^{2}} (\Gamma^{AC}\Gamma^{BD}\dot{\Gamma}_{AB}\dot{\Gamma}_{CD} + 2\Gamma^{AB}\Gamma_{CD}(R\dot{\Lambda})_{A}^{D}(R\dot{\Lambda})_{B}^{C} + 2(R\dot{\Lambda})_{C}^{B}(R\dot{\Lambda})_{B}^{C} \right]$$

$$+ 2N^{A}N^{B} \left( f_{AJ}^{L} f_{BI}^{J} + \eta^{IJ}\eta_{KL} f_{AI}^{K} f_{BJ}^{L} \right) + 4N^{K}\eta^{IJ}\dot{\eta}_{JL} f_{KI}^{L} - \Gamma^{IJ}\dot{\Gamma}_{IJ}\Gamma^{KL}\dot{\Gamma}_{KL} \right)$$

#### Ashtekar connection

$$A_{i}^{a} = \left[\frac{1}{2}\epsilon^{abc}\frac{a_{c}}{a_{b}}\Lambda_{b}^{J}R_{K}^{c}f_{IJ}^{K} - \frac{1}{4}\epsilon^{abc}\frac{1}{a_{b}a_{c}}\eta_{IJ}\Lambda_{b}^{K}\Lambda_{c}^{L}f_{LK}^{J} + \frac{\gamma}{2N}a_{(a)}R_{L}^{a}(\eta^{LJ}\dot{\eta}_{JI} + N^{A}\eta_{LK}^{LK}\eta_{LJ}f_{AK}^{J} + N^{A}f_{AL}^{L})\right]\omega_{i}^{I}$$

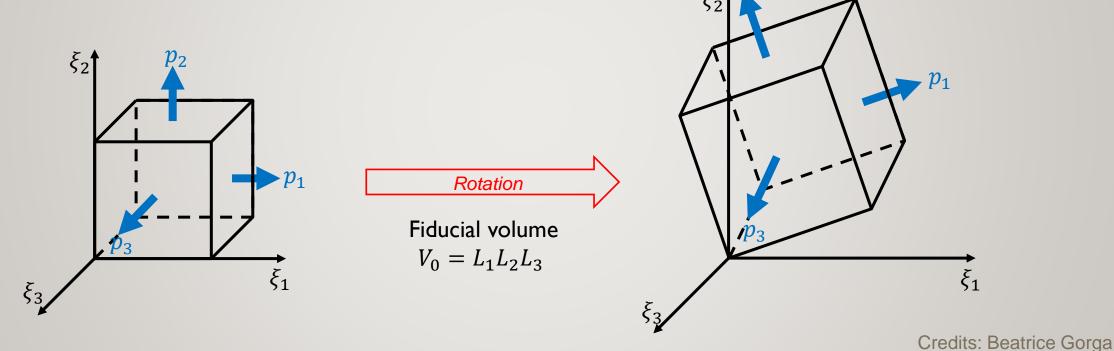
#### Electric field

$$E_a^i = |\det(\omega_i^I)| \operatorname{sgn}(a_{(a)}) |a_b a_c| \Lambda_a^I \xi_I^i$$

## Flux quantization

Quantization in the flux polarization as in [Ashtekar, Wilson-Ewing '09]

The fluxes computed on the faces of the fiducial cell



The fluxes have the same form of the diagonal case

### Hilbert space

$$\begin{cases} p_1 = a_2 a_3 \\ p_2 = a_1 a_3 \\ p_3 = a_1 a_2 \end{cases}$$

Basis states of the Hilbert space:  $|p_1, p_2, p_3, \theta, \psi, \phi\rangle$ 

$$\mathcal{H} = \bigoplus_{a \in SO(3)} \mathcal{H}_a^{diag}$$

#### Kinematical geometric operators

Volume operator 
$$Vol = V_0 \sqrt{p_1 p_2 p_3}$$
  
Area operator  $Ar(\sigma_i) = |p_i| L_i L_k \epsilon_{ijk}$ 

The kinematic depends only on the "diagonal" fluxes

Holonomy along the i-th edge

$$h_{l_i} = \exp(\lambda_i \phi_i^a \tau_a)$$

$$\phi_i^a = \begin{pmatrix} L_1 c_1 & L_2 w_3 & L_3 w_2 \\ L_1 w_3 & L_2 c_2 & L_3 w_1 \\ L_1 w_2 & L_2 w_1 & L_3 c_3 \end{pmatrix}$$

 $w_i$  functions of fluxes and angles, linear in angles velocities

## **Dynamics**

$$H = -\frac{1}{8\pi\gamma G} (p_1 p_2 c_1 c_2 + p_2 p_3 c_2 c_3 + p_1 p_3 c_1 c_3)$$
 Free diagonal part 
$$+ \left(\frac{p_1}{p_2} - \frac{p_2}{p_1}\right)^{-2} \pi_{\theta}^2$$
 
$$+ \left(\frac{p_2}{p_3} - \frac{p_3}{p_2}\right)^{-2} \left(-\cos\theta\cot\psi\,\pi_{\theta} - \sin\theta\,\pi_{\psi} + \cos\theta\csc\psi\,\pi_{\phi}\right)^2$$
 Quadratic in angles momenta 
$$+ \left(\frac{p_1}{p_3} - \frac{p_3}{p_1}\right)^{-2} \left(-\sin\theta\cot\psi\,\pi_{\theta} + \cos\theta\,\pi_{\psi} + \sin\theta\csc\psi\,\pi_{\phi}\right)^2$$
 No holonomies

## Gauge freedom

$$G_a|_{\wp_{Mt}}=0$$

$$\mathcal{D}_{Mt} = \{a_1, a_2, a_3, \theta, \psi, \phi, \pi_1, \pi_2, \pi_3, \pi_{\theta}, \pi_{\psi}, \pi_{\phi}\}$$

M. Bojowald's suggestion in [Bojowald '00, '13]

$$A_i^a(t,x) = \phi_I^a(t)\omega_i^I(x)$$

$$E_a^i(t,x) = |\det(\omega(x))|p_a^I(t)\xi_I^i(x)$$

$$G_a = \epsilon_{abc}\phi_I^b p_c^I$$

Mismatch in the number of degrees of freedom!

Recover the gauge freedom adding a rotation

$$\mathcal{D}_{\overline{Mt}} = \{a_1, a_2, a_3, \theta, \psi, \phi, \alpha, \beta, \gamma, \pi_1, \pi_2, \pi_3, \pi_\theta, \pi_\psi, \pi_\phi, \pi_\alpha, \pi_\beta, \pi_\gamma\}$$

Three abelian constraints 
$$\begin{cases} \pi_{\alpha} = 0 \\ \pi_{\beta} = 0 \\ \pi_{\gamma} = 0 \end{cases}$$

#### Canonical transformation

Lie condition  $\phi_I^a dp_a^I - \pi_n dq_n = 0$  provides, perturbative in configurational variables, a linear dependence between Gauss constraint and gauge momenta

#### Ansatz

Gauss constraint is linear in the gauge momenta  $G_a = L_{ag}\pi_g$ 

System of 9 independent equations  $\epsilon_{abc} = L_{ag}(0^t)_d^c \frac{\partial O_b^a}{\partial a_a}$ 

Admits a unique solution!

$$L_{ag} = \begin{pmatrix} -\csc\beta\cos\gamma & \sin\gamma & \cot\beta\cos\gamma \\ \csc\beta\sin\gamma & \cos\gamma & -\cot\beta\sin\gamma \end{pmatrix}$$

#### The Abelian contraints

$$G_{a} = \begin{pmatrix} -\csc\beta\cos\gamma\,\pi_{\alpha} & \sin\gamma\,\pi_{\beta} & \cot\beta\cos\gamma\,\pi_{\gamma} \\ \csc\beta\sin\gamma\,\pi_{\alpha} & \cos\gamma\,\pi_{\beta} & -\cot\beta\sin\gamma\,\pi_{\gamma} \\ 0 & 0 & \pi_{\gamma} \end{pmatrix}$$

From a SU(2) symmetry, three U(1) appear!

The Gauss constraint is recast into three abelian constraints, namely the gauge momenta

[Loran '02]

This feature holds at the quantum level 
$$\hat{G}_a |\Psi\rangle = 0 \iff \hat{\pi}_g |\Psi\rangle = 0$$

The wavefunction factorizes 
$$\Psi(p_1, p_2, p_3, \theta_1, \theta_2, \theta_3, \alpha, \beta, \gamma) = \varphi(\alpha, \beta, \gamma) \Phi(p_1, p_2, p_3, \theta_1, \theta_2, \theta_3)$$

$$\hat{\pi}_g |\Psi\rangle = 0 \Rightarrow \varphi = const$$

The Hilbert space previously defined is the gauge-invariant one

## The relation with SU(2)

$$\{G_a, G_b\}_{\wp_{\overline{Mt}}} = \epsilon_{abc}G_c$$

The Gauss constraint has the usual commutation relation on  $\wp_{\overline{Mt}}$ 

Considering the following parametrization of SO(3)  $R = \exp \alpha_i j_i$   $j_i$  generators of  $\mathfrak{so}(3)$ 

$$G = \begin{bmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & \alpha_3 & -\alpha_2 \\ -\alpha_3 & 0 & \alpha_1 \\ \alpha_2 & -\alpha_1 & 0 \end{pmatrix} + \mathcal{O}(\alpha^2) \end{bmatrix} \begin{pmatrix} \pi_1 \\ \pi_2 \\ \pi_3 \end{pmatrix}$$

$$\in \mathfrak{so}(3) \cong \mathfrak{su}(2)$$

## Conclusions

- The diagonal quantization in LQC can be extended to the nondiagonal case, in which the kinematic and the geometric operators conserve their simple expression
- The Abelianization of the quantum theory is a feature of the minisuperspace.
   The three U(1) symmetries arise from decomposing the Gauss constraint in three abelian ones
- The loop quantization of the diagonal case is quite general within the minisuperspace approach. The introduction of nondiagonal terms and the gauge freedom yield to the same kinematical picture

# Thank you for your attention

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